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## Coupled fixed points via simulation functions

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### Abstract

In the present paper, we show a result in complete metric spaces about the existence and uniqueness of coupled fixed points by using simulation functions. Moreover, we illustrate our result by presenting a theorem about the existence and uniqueness of solution to a general system of nonlinear functional-integral equations.

*Keywords:* Coupled fixed point, Simulation function, Functional-integral equation

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### 1. Introduction and preliminaries

It is well known that the Banach contraction mapping principle and its generalizations constitute a very important tool in the theory of existence of solutions to functional, differential, and integral equations. Particularly, one of these generalizations uses the so-called simulation functions.

In the sequel, we present this class of functions and the above-mentioned fixed point theorem. This material appears in [1, 2].

**Definition 1.1.** A function  $\xi : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$  is said to be a simulation function if it satisfies the following conditions:

- (i)  $\xi(0, 0) = 0$ .

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- (ii)  $\xi(t, s) < s - t$ , for any  $t, s > 0$ .  
 (iii) Let  $(t_n)$  and  $(s_n)$  be sequences in  $(0, \infty)$  such that  $\lim_{n \rightarrow \infty} t_n = \lim_{n \rightarrow \infty} s_n > 0$ , then  $\limsup_{n \rightarrow \infty} \xi(t_n, s_n) < 0$ .

In what follows, by  $\mathcal{J}$  we will denote the class of simulation functions. Examples of functions belonging to  $\mathcal{J}$  are the following ones:

- (1)  $\xi_1(t, s) = \phi_1(s) - \phi_2(t)$ , for any  $t, s \in [0, \infty)$ , where  $\phi_1, \phi_2 : [0, \infty) \rightarrow [0, \infty)$  are continuous functions such that  
 (a)  $\phi_1(t) = \phi_2(t) = 0$  if and only if  $t = 0$ ,  
 (b)  $\phi_1(t) < t \leq \phi_2(t)$  for any  $t > 0$ .  
 (2)  $\xi_2(t, s) = \varphi(s) - t$ , for any  $t, s \in [0, \infty)$ , where  $\varphi : [0, \infty) \rightarrow [0, \infty)$  is a continuous and increasing function and it satisfies that  $\varphi(t) < t$  if  $t > 0$ .

By  $\mathcal{G}$  we denote the class of functions  $\varphi$  satisfying the above mentioned conditions. It is clear that if  $\varphi \in \mathcal{G}$  then  $\varphi(0) = 0$ . Examples of functions in  $\mathcal{G}$  are  $\varphi(t) = \ln(1 + t)$ ;  $\varphi(t) = \arctan t$ ;  $\varphi(t) = \frac{t}{t+1}$ ;  $\varphi(t) = kt$  with  $k \in (0, 1)$ .

Next, we present the result about fixed point by using simulation functions that it appears in Theorem 2.8 of [1].

**Theorem 1.2.** *Let  $(X, d)$  be a complete metric space and  $T : X \rightarrow X$  a mapping such that there exists  $\xi \in \mathcal{J}$  satisfying*

$$\xi(d(T_x, T_y), d(x, y)) \geq 0,$$

for any  $x, y \in X$  with  $x \neq y$ . Then  $T$  has a unique fixed point  $x^* \in X$ . Moreover, for any  $x_0 \in X$  the Picard sequence  $(x_n)$ , where  $x_n = Tx_{n-1}$  for any  $n \in \mathbb{N}$  converges to the fixed point  $x^* \in X$ .

In this paper, we present a result about coupled fixed points. The concept of coupled fixed point was introduced by Guo and Lakshmikantham in [3] for the study of coupled quasi-solutions of an initial value problem for ordinary differential equations. Some papers on coupled fixed points have appeared in the literature (see [3, 4, 5, 6, 7, 8, 9, 10], among others). Moreover, as an application of our result, we study the existence and uniqueness of solutions to a coupled system of functional equations.

## 2. Main result

Suppose that  $(X, d)$  is a complete metric space and  $G : X \times X \rightarrow X$  a mapping.

**Definition 2.1.** An element  $(x_0, y_0) \in X \times X$  is said to be a coupled fixed point of the mapping  $G$  if  $G(x_0, y_0) = x_0$  and  $G(y_0, x_0) = y_0$ .

Now, we are ready to present our main result.

**Theorem 2.2.** *Let  $(X, d)$  be a complete metric space and  $G : X \times X \rightarrow X$  be a mapping, such that there exists  $\xi \in \mathcal{J}$  satisfying the following condition*

$$\xi\left(d(G(x, y), G(u, v)), \max(d(x, u), d(y, v))\right) \geq 0,$$

for any  $(x, y), (u, v) \in X \times X$ , with  $(x, y) \neq (u, v)$ . Then  $G$  has a unique coupled fixed point.

*Proof.* Consider the metric space  $(X \times X, \tilde{d})$  where

$$\tilde{d}((x, y), (u, v)) = \max(d(x, u), d(y, v)),$$

for any  $(x, y), (u, v) \in X \times X$ .

It is well known that  $(X \times X, \tilde{d})$  is also a complete metric space.

Next, we define the following mapping  $\tilde{G} : X \times X \rightarrow X \times X$  by

$$\tilde{G}(x, y) = (G(x, y), G(y, x)).$$

In what follows, we check that  $\tilde{G}$  satisfies assumptions of Theorem 1.2.

In fact, for any  $x, y, u, v \in X$ , we have that

$$\begin{aligned} \tilde{d}(\tilde{G}(x, y), \tilde{G}(u, v)) &= \tilde{d}\left((G(x, y), G(y, x)), (G(u, v), G(v, u))\right) = \\ &= \max\left(d(G(x, y), G(u, v)), d(G(y, x), G(v, u))\right). \end{aligned}$$

In this point, we can consider two cases:

- (a)  $\tilde{d}(\tilde{G}(x, y), \tilde{G}(u, v)) = d(G(x, y), G(u, v))$ ,
- (b)  $\tilde{d}(\tilde{G}(x, y), \tilde{G}(u, v)) = d(G(y, x), G(v, u))$ .

**Case (a).** Taking into account our assumption, we infer

$$\begin{aligned} &\xi\left(\tilde{d}(\tilde{G}(x, y), \tilde{G}(u, v)), \tilde{d}((x, y), (u, v))\right) = \\ &= \xi\left(d(G(x, y), G(u, v)), \max(d(x, u), d(y, v))\right) \geq 0. \end{aligned}$$

This proves that the condition appearing in Theorem 1.2 is satisfied for the complete metric space  $(X \times X, \tilde{d})$ .

**Case (b).** By using similar argument to case (a), we get

$$\begin{aligned} &\xi\left(\tilde{d}(\tilde{G}(x, y), \tilde{G}(u, v)), \tilde{d}((x, y), (u, v))\right) = \\ &= \xi\left(d(G(y, x), G(v, u)), \max(d(x, u), d(y, v))\right) = \\ &= \xi\left(d(G(y, x), G(v, u)), \max(d(y, v), d(x, u))\right) \geq 0. \end{aligned}$$

In this case, we have also proved that the condition of Theorem 1.2 holds.

Now, by Theorem 1.2, the mapping  $\tilde{G}$  has a unique fixed point. This is, there exists a unique pair  $(u_0, v_0) \in X \times X$  such that

$$\tilde{G}(u_0, v_0) = (u_0, v_0).$$

Taking into account the definition of  $\tilde{G}$ , we deduce that

$$\tilde{G}(u_0, v_0) = (G(u_0, v_0), G(v_0, u_0)) = (u_0, v_0),$$

and from this

$$G(u_0, v_0) = u_0 \quad \text{and} \quad G(v_0, u_0) = v_0.$$

This is,  $(u_0, v_0) \in X \times X$  is a coupled fixed point of the mapping  $G$ .

It is easily seen that the uniqueness of the coupled fixed point  $(u_0, v_0)$  is obtained of the uniqueness of the fixed point  $(u_0, v_0)$  for  $\tilde{G}$ .

This completes the proof.

□

### 3. Applications

In this section, we illustrate our result studying the existence and uniqueness of solutions to the following coupled system of functional-integral equations

$$\begin{cases} x(t) = f\left(t, x(t), y(t), \int_0^t g(s, x(s), y(s)) ds\right) \\ y(t) = f\left(t, y(t), x(t), \int_0^t g(s, y(s), x(s)) ds\right), \end{cases} \quad (1)$$

for  $t \in [0, 1]$ , in  $C[0, 1] \times C[0, 1]$ .

In the following theorem, we present a sufficient condition for the existence and uniqueness of solutions to Problem (1).

**Theorem 3.1.** *Suppose the following assumptions:*

- (i)  $f : [0, 1] \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  and  $g : [0, 1] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  are continuous functions.
- (ii) There exists  $\varphi \in \mathcal{G}$  such that

$$|f(t, x, y, z) - f(t, u, v, w)| \leq \varphi(\max(|x - u|, |y - v|, |z - w|)),$$

for any  $t \in [0, 1]$  and  $x, y, z, u, v, w \in \mathbb{R}$ .

(Here,  $\mathcal{G}$  is the class of functions appearing in section 1).

- (iii) The following inequality

$$|g(t, x, y) - g(t, u, v)| \leq \max(|x - u|, |y - v|),$$

for any  $t \in [0, 1]$  and  $x, y, u, v \in \mathbb{R}$ , holds.

Then Problem (1) has a unique solution  $(x, y) \in C[0, 1] \times C[0, 1]$ .

*Proof.* Consider the operator  $F$  defined on  $C[0, 1] \times C[0, 1]$  by

$$F(x, y)(t) = f\left(t, x(t), y(t), \int_0^t g(s, x(s), y(s)) ds\right),$$

for any  $t \in [0, 1]$ .

From i, it follows that  $F$  applies  $C[0, 1] \times C[0, 1]$  into  $C, [0, 1]$ .

Now, we check that  $F$  satisfies the condition appearing in Theorem 2.2.

In fact, by using our assumptions, we have, for any  $(x, y), (u, v) \in C[0, 1] \times C[0, 1]$  with  $(x, y) \neq (u, v)$ , that

$$\begin{aligned} d(F(x, y), F(u, v)) &= \sup_{0 \leq t \leq 1} |F(x, y)(t) - F(u, v)(t)| = \\ &= \sup_{0 \leq t \leq 1} \left| f\left(t, x(t), y(t), \int_0^t g(s, x(s), y(s)) ds\right) \right. \\ &\quad \left. - f\left(t, u(t), v(t), \int_0^t g(s, u(s), v(s)) ds\right) \right| \\ &\leq \sup_{0 \leq t \leq 1} \varphi\left(\max(|x(t) - u(t)|, |y(t) - v(t)|, \left| \int_0^t g(s, x(s), y(s)) - g(s, u(s), v(s)) ds \right|)\right) \\ &\leq \sup_{0 \leq t \leq 1} \varphi\left(\max(d(x, u), d(y, v), \int_0^t |g(s, x(s), y(s)) - g(s, u(s), v(s))| ds)\right) \\ &\leq \sup_{0 \leq t \leq 1} \varphi\left(\max(d(x, u), d(y, v), \int_0^t \max(|x(s) - u(s)|, |y(s) - v(s)|) ds)\right) \\ &\leq \sup_{0 \leq t \leq 1} \varphi\left(\max(d(x, u), d(y, v), \max(d(x, u), d(y, v)))\right) \\ &\leq \sup_{0 \leq t \leq 1} \varphi\left(\max(d(x, u), d(y, v))\right), \end{aligned}$$

where we have used the fact that  $\varphi$  is increasing.  
 From the last inequality, we deduce that

$$\varphi\left(\max(d(x, u), d(y, v))\right) - d(F(x, y), F(u, v)) \geq 0. \tag{2}$$

Now, taking into account that if we put  $\xi(t, s) = \varphi(s) - t$ , then, as we saw in section 1,  $\xi \in \mathcal{J}$  and (2)

$$\xi\left(d(F(x, y), F(u, v)), \max(d(x, u), d(y, v))\right) \geq 0.$$

This proves that assumption of Theorem 2.2 is satisfied.

Therefore,  $F$  has a unique coupled fixed point  $(x_0, y_0)$ . This means that  $(x_0, y_0) \in C[0, 1] \times C[0, 1]$ ,  $F(x_0, y_0) = x_0$  and  $F(y_0, x_0) = y_0$ , or, equivalently, for any  $t \in [0, 1]$

$$\begin{aligned} x_0(t) &= f\left(t, x_0(t), y_0(t), \int_0^t g(s, x_0(s), y_0(s)) ds\right) \\ y_0(t) &= f\left(t, y_0(t), x_0(t), \int_0^t g(s, y_0(s), x_0(s)) ds\right). \end{aligned}$$

This proves that  $(x_0, y_0) \in C[0, 1] \times C[0, 1]$  is a unique solution to Problem (1). □

Next, we present a particular numerical example.

**Remark 3.2.** In our example, we will use the function  $f : \mathbb{R}_+ \rightarrow \mathbb{R}$  given by  $f(x) = \ln(1 + x)$ . This function, as it is concave and  $f(0) = 0$ , a well known result says us that

$$|\ln(1 + x) - \ln(1 + y)| \leq \ln(1 + |x - y|),$$

for any  $x, y \in \mathbb{R}_+$ .

We are ready to present our numerical example.

**Example 3.3.** Consider the following coupled system of integral equations

$$\begin{cases} x(t) = t^2 + \frac{1}{3} \left( \ln\left(1 + \frac{|x(t)|}{2}\right) + \ln(1 + |y(t)|) \right) + \\ \quad + \ln\left(1 + \int_0^t \lambda(s^2 + |x(s)| + |y(s)|) ds\right) \\ y(t) = t^2 + \frac{1}{3} \left( \ln\left(1 + \frac{|y(t)|}{2}\right) + \ln(1 + |x(t)|) \right) + \\ \quad + \ln\left(1 + \int_0^t \lambda(s^2 + |x(s)| + |y(s)|) ds\right), \end{cases} \tag{3}$$

for any  $t \in [0, 1]$  with  $\lambda > 0$ . Notice that Problem (3) is a particular of Problem (1) with

$$f(t, x, y, z) = t^2 + \frac{1}{3} \left( \ln\left(1 + \frac{|x|}{2}\right) + \ln(1 + |y|) + \ln(1 + |z|) \right),$$

and

$$g(t, x, y) = \lambda (t^2 + |x| + |y|).$$

It is clear that  $f$  and  $g$  are continuous functions on  $[0, 1] \times \mathbb{R} \times \mathbb{R} \times \mathbb{R}$  and on  $[0, 1] \times \mathbb{R} \times \mathbb{R}$ , respectively. Therefore, assumption i of Theorem 3.1 is satisfied. Moreover, for any  $t \in [0, 1]$  and  $x, y, z, u, v, w \in \mathbb{R}$ , we

have

$$\begin{aligned}
|f(t, x, y, z) - f(t, u, v, w)| &= \frac{1}{3} \left| \ln \left( 1 + \frac{|x|}{2} \right) + \ln(1 + |y|) + \ln(1 + |z|) - \right. \\
&\quad \left. - \ln \left( 1 + \frac{|u|}{2} \right) - \ln(1 + |v|) - \ln(1 + |w|) \right| \\
&\leq \frac{1}{3} \left[ \left| \ln \left( 1 + \frac{|x|}{2} \right) - \ln \left( 1 + \frac{|u|}{2} \right) \right| + \right. \\
&\quad \left. + \left| \ln(1 + |y|) - \ln(1 + |v|) \right| + \left| \ln(1 + |z|) - \ln(1 + |w|) \right| \right] \\
&\leq \frac{1}{3} \left[ \ln \left( 1 + \left| \frac{|x|}{2} - \frac{|u|}{2} \right| \right) + \ln(1 + ||y| - |v||) + \right. \\
&\quad \left. + \ln(1 + ||z| - |w||) \right] \\
&\leq \frac{1}{3} \left[ \ln \left( 1 + \frac{|x - u|}{2} \right) + \ln(1 + |y - v|) + \ln(1 + |z - u|) \right] \\
&\leq \frac{1}{3} \left[ \ln(1 + |x - u|) + \ln(1 + |y - v|) + \ln(1 + |z - u|) \right] \\
&\leq \frac{1}{3} \left[ 3 \ln \left( 1 + \max(|x - u|, |y - v|, |z - u|) \right) \right] \\
&\leq \ln \left( 1 + \max(|x - u|, |y - v|, |z - u|) \right), \tag{4}
\end{aligned}$$

where we have used Remark 3.2, the inequality  $||x| - |y|| \leq |x - y|$ , for any  $x, y \in \mathbb{R}$  and the increasing character of the function  $f(x) = \ln(1 + x)$  for  $x \geq 0$ . From 4, we infer that assumption ii of Theorem 3.1 is satisfied with the function  $\varphi(t) = \ln(1 + t)$ . It is easily seen that  $\varphi \in \mathcal{G}$ .

On the other hand, for any  $t \in [0, 1]$  and  $x, y, u, v \in \mathbb{R}$ , we have

$$\begin{aligned}
|g(t, x, y) - g(t, u, v)| &= \lambda ||x| + |y| - |u| - |v|| \leq \\
&\leq \lambda (||x| - |u|| + ||y| - |v||) \leq \\
&\leq \lambda (|x - u| + |y - v|) \leq \\
&\leq 2\lambda \max(|x - u|, |y - v|).
\end{aligned}$$

Therefore, if  $2\lambda \leq 1$ , this is, if  $0 \leq \lambda \leq \frac{1}{2}$ , then assumption iii of Theorem 3.1 is satisfied.

Finally, by Theorem 3.1, we deduce that if  $0 \leq \lambda \leq \frac{1}{2}$ , Problem (3) has a unique solution  $(x_0, y_0) \in C[0, 1] \times C[0, 1]$ .

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